

2024



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# AP<sup>®</sup> Physics C: Electricity and Magnetism

## Free-Response Questions Set 1

## ADVANCED PLACEMENT PHYSICS C TABLE OF INFORMATION

CONSTANTS AND CONVERSION FACTORS	
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude, $e = 1.60 \times 10^{-19}$ C
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	1 electron volt, $1 \text{ eV} = 1.60 \times 10^{-19}$ J
Electron mass, $m_e = 9.11 \times 10^{-31}$ kg	Speed of light, $c = 3.00 \times 10^8$ m/s
Avogadro's number, $N_0 = 6.02 \times 10^{23}$ mol <sup>-1</sup>	Universal gravitational constant, $G = 6.67 \times 10^{-11}$ (N·m <sup>2</sup> )/kg <sup>2</sup>
Universal gas constant, $R = 8.31$ J/(mol·K)	Acceleration due to gravity at Earth's surface, $g = 9.8$ m/s <sup>2</sup>
Boltzmann's constant, $k_B = 1.38 \times 10^{-23}$ J/K	
1 unified atomic mass unit,	$1 \text{ u} = 1.66 \times 10^{-27}$ kg = 931 MeV/c <sup>2</sup>
Planck's constant,	$h = 6.63 \times 10^{-34}$ J·s = $4.14 \times 10^{-15}$ eV·s
	$hc = 1.99 \times 10^{-25}$ J·m = $1.24 \times 10^3$ eV·nm
Vacuum permittivity,	$\epsilon_0 = 8.85 \times 10^{-12}$ C <sup>2</sup> /(N·m <sup>2</sup> )
Coulomb's law constant, $k = 1/(4\pi\epsilon_0) = 9.0 \times 10^9$ (N·m <sup>2</sup> )/C <sup>2</sup>	
Vacuum permeability,	$\mu_0 = 4\pi \times 10^{-7}$ (T·m)/A
Magnetic constant, $k' = \mu_0/(4\pi) = 1 \times 10^{-7}$ (T·m)/A	
1 atmosphere pressure,	$1 \text{ atm} = 1.0 \times 10^5$ N/m <sup>2</sup> = $1.0 \times 10^5$ Pa

UNIT SYMBOLS	meter, m	mole, mol	watt, W	farad, F
	kilogram, kg	hertz, Hz	coulomb, C	tesla, T
	second, s	newton, N	volt, V	degree Celsius, °C
	ampere, A	pascal, Pa	ohm, Ω	electron volt, eV
	kelvin, K	joule, J	henry, H	

PREFIXES		
Factor	Prefix	Symbol
$10^9$	giga	G
$10^6$	mega	M
$10^3$	kilo	k
$10^{-2}$	centi	c
$10^{-3}$	milli	m
$10^{-6}$	micro	μ
$10^{-9}$	nano	n
$10^{-12}$	pico	p

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
$\theta$	$0^\circ$	$30^\circ$	$37^\circ$	$45^\circ$	$53^\circ$	$60^\circ$	$90^\circ$
$\sin \theta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
$\tan \theta$	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	$\infty$

The following assumptions are used in this exam.

- I. The frame of reference of any problem is inertial unless otherwise stated.
- II. The direction of current is the direction in which positive charges would drift.
- III. The electric potential is zero at an infinite distance from an isolated point charge.
- IV. All batteries and meters are ideal unless otherwise stated.
- V. Edge effects for the electric field of a parallel plate capacitor are negligible unless otherwise stated.

## ADVANCED PLACEMENT PHYSICS C EQUATIONS

## MECHANICS

$$v_x = v_{x0} + a_x t$$

$$x = x_0 + v_{x0} t + \frac{1}{2} a_x t^2$$

$$v_x^2 = v_{x0}^2 + 2a_x(x - x_0)$$

$$\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$$

$$\vec{F} = \frac{d\vec{p}}{dt}$$

$$\vec{J} = \int \vec{F} dt = \Delta\vec{p}$$

$$\vec{p} = m\vec{v}$$

$$|\vec{F}_f| \leq \mu |\vec{F}_N|$$

$$\Delta E = W = \int \vec{F} \cdot d\vec{r}$$

$$K = \frac{1}{2} m v^2$$

$$P = \frac{dE}{dt}$$

$$P = \vec{F} \cdot \vec{v}$$

$$\Delta U_g = mg\Delta h$$

$$a_c = \frac{v^2}{r} = \omega^2 r$$

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$$

$$I = \int r^2 dm = \sum mr^2$$

$$x_{cm} = \frac{\sum m_i x_i}{\sum m_i}$$

$$v = r\omega$$

$$\vec{L} = \vec{r} \times \vec{p} = I\vec{\omega}$$

$$K = \frac{1}{2} I \omega^2$$

$$\omega = \omega_0 + \alpha t$$

$$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

$a$  = acceleration  
 $E$  = energy  
 $F$  = force  
 $f$  = frequency  
 $h$  = height  
 $I$  = rotational inertia  
 $J$  = impulse  
 $K$  = kinetic energy  
 $k$  = spring constant  
 $\ell$  = length  
 $L$  = angular momentum  
 $m$  = mass  
 $P$  = power  
 $p$  = momentum  
 $r$  = radius or distance  
 $T$  = period  
 $t$  = time  
 $U$  = potential energy  
 $v$  = velocity or speed  
 $W$  = work done on a system  
 $x$  = position  
 $\mu$  = coefficient of friction  
 $\theta$  = angle  
 $\tau$  = torque  
 $\omega$  = angular speed  
 $\alpha$  = angular acceleration  
 $\phi$  = phase angle

$$\vec{F}_s = -k\Delta\vec{x}$$

$$U_s = \frac{1}{2} k (\Delta x)^2$$

$$x = x_{max} \cos(\omega t + \phi)$$

$$T = \frac{2\pi}{\omega} = \frac{1}{f}$$

$$T_s = 2\pi \sqrt{\frac{m}{k}}$$

$$T_p = 2\pi \sqrt{\frac{\ell}{g}}$$

$$|\vec{F}_G| = \frac{Gm_1 m_2}{r^2}$$

$$U_G = -\frac{Gm_1 m_2}{r}$$

## ELECTRICITY AND MAGNETISM

$$|\vec{F}_E| = \frac{1}{4\pi\epsilon_0} \left| \frac{q_1 q_2}{r^2} \right|$$

$$\vec{E} = \frac{\vec{F}_E}{q}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon_0}$$

$$E_x = -\frac{dV}{dx}$$

$$\Delta V = -\int \vec{E} \cdot d\vec{r}$$

$$V = \frac{1}{4\pi\epsilon_0} \sum_i \frac{q_i}{r_i}$$

$$U_E = qV = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r}$$

$$\Delta V = \frac{Q}{C}$$

$$C = \frac{\kappa \epsilon_0 A}{d}$$

$$C_p = \sum_i C_i$$

$$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$$

$$I = \frac{dQ}{dt}$$

$$U_C = \frac{1}{2} Q\Delta V = \frac{1}{2} C (\Delta V)^2$$

$$R = \frac{\rho \ell}{A}$$

$$\vec{E} = \rho \vec{J}$$

$$I = Nev_d A$$

$$I = \frac{\Delta V}{R}$$

$$R_s = \sum_i R_i$$

$$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$$

$$P = I\Delta V$$

$A$  = area  
 $B$  = magnetic field  
 $C$  = capacitance  
 $d$  = distance  
 $E$  = electric field  
 $\mathcal{E}$  = emf  
 $F$  = force  
 $I$  = current  
 $J$  = current density  
 $L$  = inductance  
 $\ell$  = length  
 $n$  = number of loops of wire per unit length  
 $N$  = number of charge carriers per unit volume  
 $P$  = power  
 $Q$  = charge  
 $q$  = point charge  
 $R$  = resistance  
 $r$  = radius or distance  
 $t$  = time  
 $U$  = potential or stored energy  
 $V$  = electric potential  
 $v$  = velocity or speed  
 $\rho$  = resistivity  
 $\Phi$  = flux  
 $\kappa$  = dielectric constant

$$\vec{F}_M = q\vec{v} \times \vec{B}$$

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I$$

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{\ell} \times \hat{r}}{r^2}$$

$$\vec{F} = \int I d\vec{\ell} \times \vec{B}$$

$$B_s = \mu_0 n I$$

$$\Phi_B = \int \vec{B} \cdot d\vec{A}$$

$$\mathcal{E} = \oint \vec{E} \cdot d\vec{\ell} = -\frac{d\Phi_B}{dt}$$

$$\mathcal{E} = -L \frac{dI}{dt}$$

$$U_L = \frac{1}{2} LI^2$$

## ADVANCED PLACEMENT PHYSICS C EQUATIONS

## GEOMETRY AND TRIGONOMETRY

Rectangle

$$A = bh$$

Triangle

$$A = \frac{1}{2}bh$$

Circle

$$A = \pi r^2$$

$$C = 2\pi r$$

$$s = r\theta$$

Rectangular Solid

$$V = \ell wh$$

Cylinder

$$V = \pi r^2 \ell$$

$$S = 2\pi r \ell + 2\pi r^2$$

Sphere

$$V = \frac{4}{3}\pi r^3$$

$$S = 4\pi r^2$$

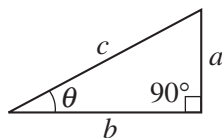
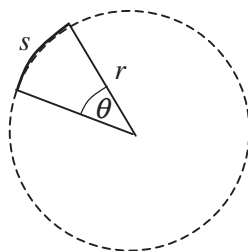
Right Triangle

$$a^2 + b^2 = c^2$$

$$\sin \theta = \frac{a}{c}$$

$$\cos \theta = \frac{b}{c}$$

$$\tan \theta = \frac{a}{b}$$

 $A$  = area $C$  = circumference $V$  = volume $S$  = surface area $b$  = base $h$  = height $\ell$  = length $w$  = width $r$  = radius $s$  = arc length $\theta$  = angle

## CALCULUS

$$\frac{df}{dx} = \frac{df}{du} \frac{du}{dx}$$

$$\frac{d}{dx}(x^n) = nx^{n-1}$$

$$\frac{d}{dx}(e^{ax}) = ae^{ax}$$

$$\frac{d}{dx}(\ln ax) = \frac{1}{x}$$

$$\frac{d}{dx}[\sin(ax)] = a \cos(ax)$$

$$\frac{d}{dx}[\cos(ax)] = -a \sin(ax)$$

$$\int x^n dx = \frac{1}{n+1} x^{n+1}, n \neq -1$$

$$\int e^{ax} dx = \frac{1}{a} e^{ax}$$

$$\int \frac{dx}{x+a} = \ln|x+a|$$

$$\int \cos(ax) dx = \frac{1}{a} \sin(ax)$$

$$\int \sin(ax) dx = -\frac{1}{a} \cos(ax)$$

## VECTOR PRODUCTS

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$|\vec{A} \times \vec{B}| = AB \sin \theta$$

Begin your response to **QUESTION 1** on this page.

**PHYSICS C: ELECTRICITY AND MAGNETISM**

**SECTION II**

**Time—45 minutes**

**3 Questions**

**Directions:** Answer all three questions. The suggested time is about 15 minutes for answering each of the questions, which are worth 15 points each. The parts within a question may not have equal weight. Show all your work in this booklet in the spaces provided after each part.

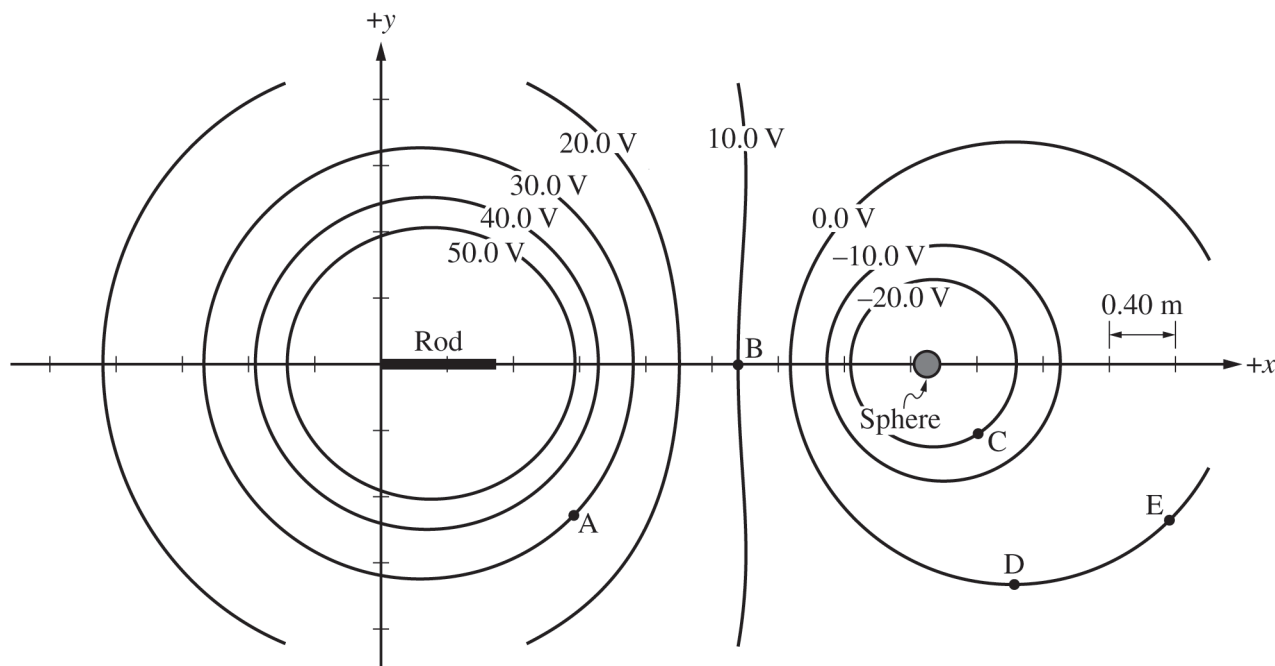


Figure 1

1. A nonconducting rod of uniform positive linear charge density is near a sphere with charge  $-2.0$  nC. The rod and sphere are held at rest on the  $x$ -axis, as shown in Figure 1. Equipotential lines and positions A, B, C, D, and E are labeled. Adjacent tick marks on the  $x$ -axis and the  $y$ -axis are 0.40 m apart.
- (a) **Calculate** the absolute value of the electric flux through the Gaussian surface whose cross section is the  $-20.0$  V equipotential line.

**GO ON TO THE NEXT PAGE.**

Continue your response to **QUESTION 1** on this page.

A positive test charge (not shown) is placed and held at rest at Position C. An external force is applied to the test charge to move the test charge to different positions in the order of  $C \rightarrow E \rightarrow D \rightarrow A$ . The test charge is momentarily held at rest at each position.

(b) The bar shown in Figure 2 represents the absolute value of the work  $W_{CE}$  done by the external force on the test charge to move the test charge from Position C to Position E.

i. Complete the following tasks on Figure 2.

- **Draw** a bar to represent the relative absolute value of the work  $W_{ED}$  done by the external force on the test charge to move the test charge from Position E to Position D.
- **Draw** a bar to represent the relative absolute value of the work  $W_{DA}$  done by the external force on the test charge to move the test charge from Position D to Position A.
- The height of each bar should be proportional to the value of  $W_{CE}$ . If  $W_{ED} = 0$  and/or  $W_{DA} = 0$ , write a “0” in the corresponding columns, as appropriate.

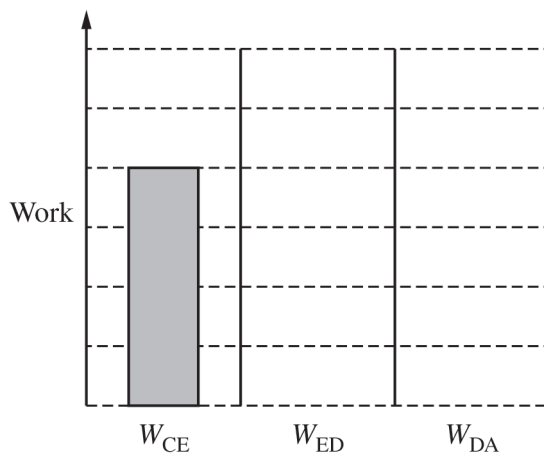


Figure 2

ii. **Calculate** the approximate magnitude of the  $x$ -component of the electric field at Position B.

**GO ON TO THE NEXT PAGE.**

Continue your response to **QUESTION 1** on this page.

The positive test charge is placed at Position D. The test charge is then released from rest.

(c) **Indicate** the direction (not components) of the net electric force exerted on the test charge immediately after the test charge is released from rest.

\_\_\_\_\_  $+x$       \_\_\_\_\_  $+y$       \_\_\_\_\_ Directly away from the sphere

\_\_\_\_\_  $-x$       \_\_\_\_\_  $-y$       \_\_\_\_\_ Directly toward the sphere

Without using equations, **justify** your answer using physics principles.

**GO ON TO THE NEXT PAGE.**

Continue your response to **QUESTION 1** on this page.

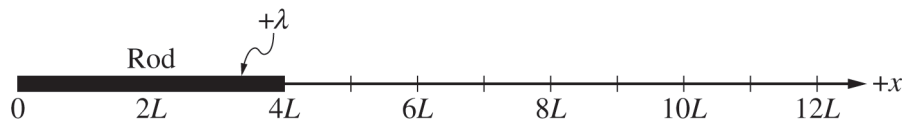


Figure 3

The sphere and the test charge are removed. The rod has length  $4L$  and uniform positive linear charge density  $+\lambda$ . The rod is held at rest on the  $x$ -axis in the orientation shown in Figure 3. Position P (not shown) is located on the  $x$ -axis a distance  $x_P$  from the origin, where  $x_P > 4L$ .

(d) The electric potential  $V_P$  at  $x_P$  is  $V_P = k\lambda \ln\left(\frac{x_P}{x_P - 4L}\right)$ .

i. Using integral calculus, **derive** the expression for  $V_P$  provided.

**GO ON TO THE NEXT PAGE.**



Continue your response to **QUESTION 1** on this page.

- ii. On Figure 4, **sketch** a graph of the  $x$ -component  $E_x$  of the electric field from the rod as a function of  $x$  in the region  $4L < x < 12L$ .

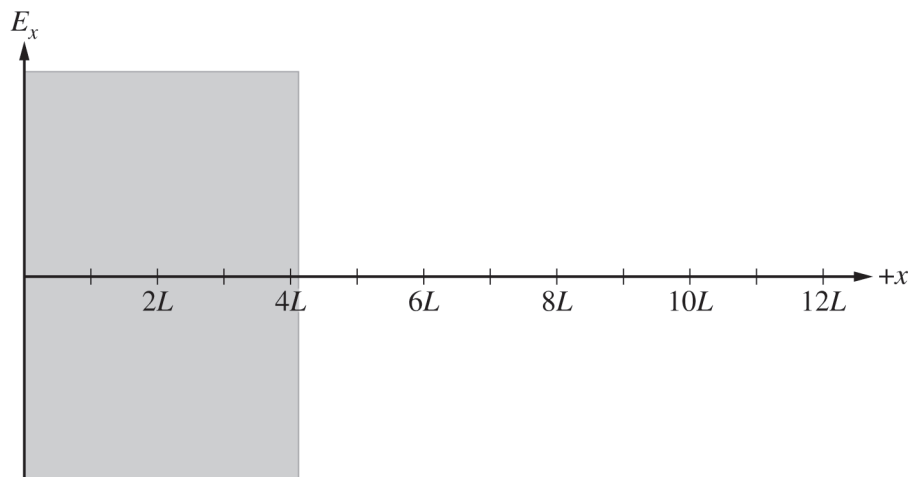


Figure 4

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Begin your response to **QUESTION 2** on this page.

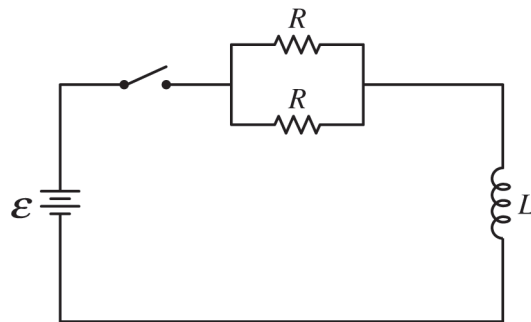


Figure 1

2. Students are asked to determine the resistance  $R$  of two identical resistors. The resistors are in parallel with each other and are connected in series to a battery of known emf  $\mathcal{E}$ , an inductor of known inductance  $L$ , and a switch, as shown in Figure 1. The students have access to a voltmeter that can measure potential difference as a function of time. The students are required to measure a quantity that decreases with time to determine  $R$ .

(a)

- i. On the circuit diagram shown in Figure 1, **draw** the voltmeter, using the following symbol, with connections that would allow the students to correctly measure a potential difference that decreases with time.



Voltmeter Symbol

- ii. **Describe** a procedure for collecting data that would allow the students to graphically determine the experimental value for  $R$  using the measured quantity that decreases with time. Provide enough detail so that another student could replicate the experiment.

**GO ON TO THE NEXT PAGE.**

Continue your response to **QUESTION 2** on this page.

(b)

i. On the axes shown in Figure 2, produce a graph that represents the expected trend of the data by completing the following tasks.

- **Label** the quantities graphed on the vertical and horizontal axes.
- **Sketch** a line or curve that represents the expected trend of the collected data.
- **Label** any appropriate intercepts and/or asymptotes in terms of the quantities provided.



Figure 2

ii. **Describe** how the information from the graph in part (b)(i) would be used to determine the experimental value for  $R$ .

**GO ON TO THE NEXT PAGE.**

Continue your response to **QUESTION 2** on this page.

- (c) Starting with an appropriate application of Kirchhoff's loop rule, **derive**, but do NOT solve, a differential equation that can be used to determine the current  $I$  in the inductor at time  $t$  after the switch is closed. Express your answer in terms of  $R$ ,  $\mathcal{E}$ ,  $L$ ,  $t$ , and physical constants, as appropriate.

After reaching steady state, the absolute value of the potential difference across the inductor is  $|\Delta V_1|$ . The students replace the original inductor with a new inductor that has nonnegligible resistance. The experiment is repeated. After a long time, the absolute value of the potential difference across the new inductor is  $|\Delta V_2|$ .

- (d) **Indicate** whether  $|\Delta V_2|$  is greater than, less than, or equal to  $|\Delta V_1|$ .

\_\_\_\_\_  $|\Delta V_2| > |\Delta V_1|$       \_\_\_\_\_  $|\Delta V_2| < |\Delta V_1|$       \_\_\_\_\_  $|\Delta V_2| = |\Delta V_1|$

**Justify** your answer.

**GO ON TO THE NEXT PAGE.**

Begin your response to **QUESTION 3** on this page.

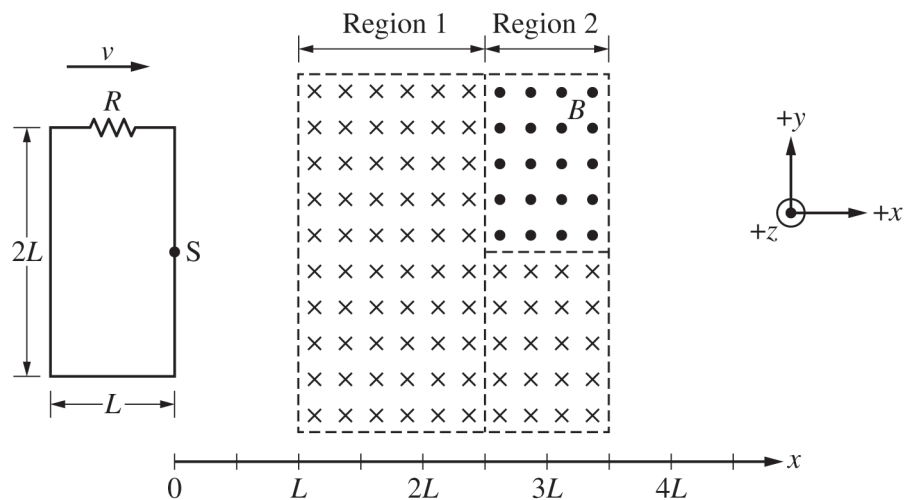


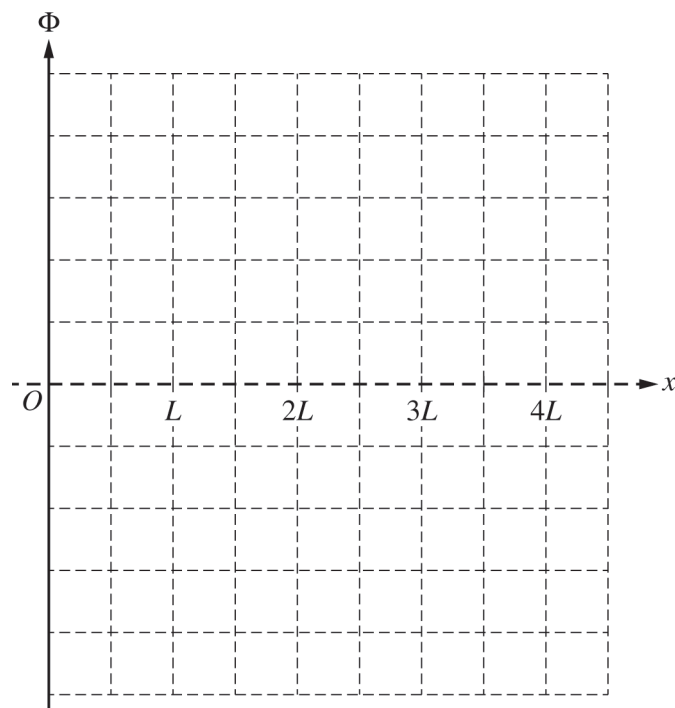
Figure 1

3. A wire is connected to a resistor of resistance  $R$  to form a rigid rectangular loop of width  $L$  and height  $2L$ . An external force is exerted on the loop so that the loop always moves with constant speed  $v$  in the  $+x$ -direction, as shown in Figure 1. The loop then enters Region 1 of external uniform magnetic field of magnitude  $B$  that is directed in the  $-z$ -direction. Region 1 has boundaries  $x = L$  and  $x = 2.5L$ . The loop later enters Region 2 with two external, uniform magnetic fields, each of magnitude  $B$ , that are parallel but are directed in opposite  $z$ -directions. Region 2 has boundaries  $x = 2.5L$  and  $x = 3.5L$ . Point S is the midpoint of the leading edge of the loop and is aligned with the horizontal boundary in Region 2 that separates the two magnetic fields.

**GO ON TO THE NEXT PAGE.**

Continue your response to **QUESTION 3** on this page.

- (a) On the following axes, **sketch** a graph of the magnetic flux  $\Phi$  through the rectangular loop as a function of the position  $x$  of Point S from  $x = 0$  to  $x = 4.5L$ . The  $+z$ -direction indicated in Figure 1 corresponds to  $+\Phi$ .



- (b) Consider the instant when Point S reaches  $x = 1.5L$ .

i. **Indicate** whether the current  $I_R$  that is induced in the rectangular loop when Point S reaches  $x = 1.5L$  is clockwise, counterclockwise, or zero.

\_\_\_\_\_ Clockwise      \_\_\_\_\_ Counterclockwise      \_\_\_\_\_ Zero

Briefly **justify** your answer.

**GO ON TO THE NEXT PAGE.**

Continue your response to **QUESTION 3** on this page.

ii. **Derive** an expression for  $I_R$  when Point S reaches  $x = 1.5L$ . If  $I_R = 0$ , indicate how the derived expression shows that  $I_R = 0$ . Express your answer in terms of  $R$ ,  $L$ ,  $v$ ,  $B$ , and physical constants, as appropriate.

iii. **Derive** an expression for the power  $P$  dissipated by the resistor when Point S reaches  $x = 1.5L$ . Express your answer in terms of  $R$ ,  $L$ ,  $v$ ,  $B$ , and physical constants, as appropriate.

**GO ON TO THE NEXT PAGE.**

Continue your response to **QUESTION 3** on this page.

The total energy dissipated by the resistor in the rectangular loop as Point S moves from  $x = 0$  to  $x = 4.5L$  is  $E_{\text{original}}$ .

The vertical boundary between regions 1 and 2 is now shifted to  $x = 1.5L$ . After the boundary is shifted, the rectangular loop again moves with speed  $v$  in the  $+x$ -direction, as shown in Figure 2. The total energy dissipated by the resistor as Point S moves from  $x = 0$  to  $x = 4.5L$  is  $E_{\text{new}}$ .

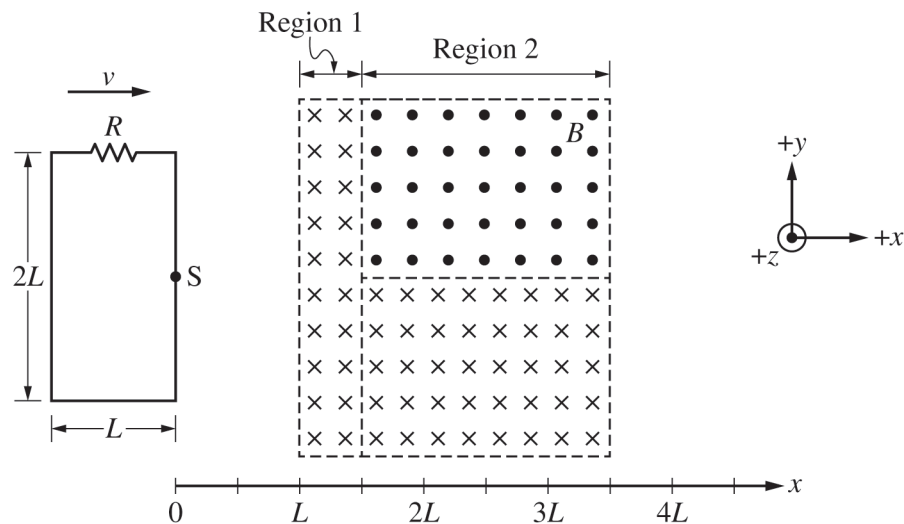


Figure 2

(c) **Indicate** whether  $E_{\text{new}}$  is greater than, less than, or equal to  $E_{\text{original}}$ .

\_\_\_\_\_  $E_{\text{new}} > E_{\text{original}}$       \_\_\_\_\_  $E_{\text{new}} < E_{\text{original}}$       \_\_\_\_\_  $E_{\text{new}} = E_{\text{original}}$

Briefly **justify** your answer.

**GO ON TO THE NEXT PAGE.**



Continue your response to **QUESTION 3** on this page.

The original magnetic fields are modified so that the region  $L < x < 3.5L$  contains an external uniform magnetic field of magnitude  $B$  that is directed in the  $-z$ -direction.

A new wire is connected to a resistor of resistance  $R$  to form a rigid triangular loop with base length  $L$  and height  $2L$ . An external force is exerted on the loop so that the loop always moves with speed  $v$  in the  $+x$ -direction, as shown in Figure 3. Point S represents the lower-leading corner of the loop.

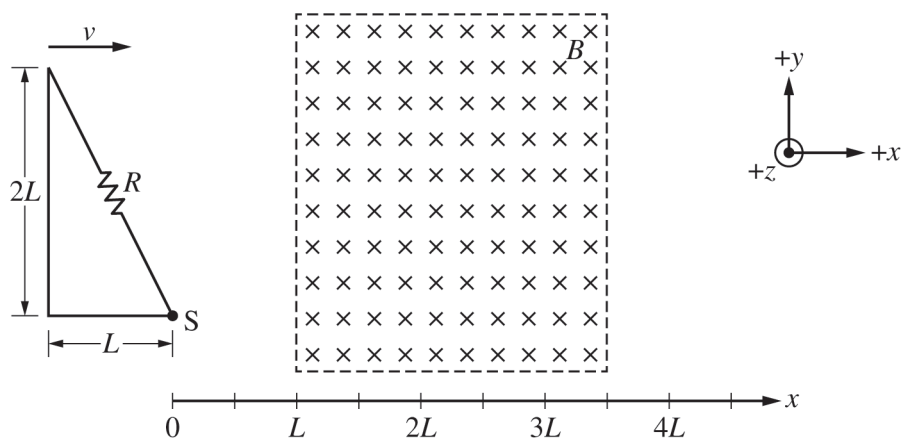
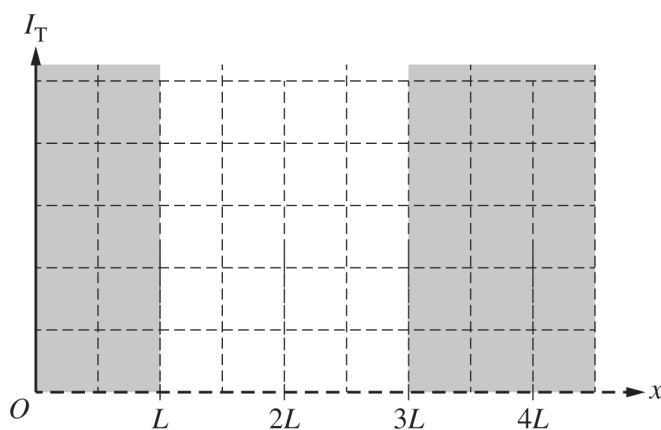


Figure 3

(d) On the following axes, **sketch** a graph of the induced current  $I_T$  in the triangular loop as Point S moves from  $x = L$  to  $x = 3L$ .



**GO ON TO THE NEXT PAGE.**

**STOP**

**END OF EXAM**