2023



# AP<sup>°</sup> Physics C: Mechanics

Scoring Guidelines Set 2

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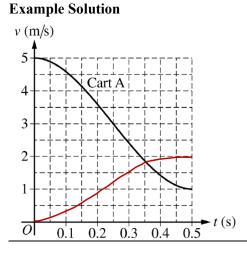
# Question 1: Free-Response Question15 points(a)(i)For stating that the area bounded by the curve is the displacement1 point(a)(ii)For indicating momentum is conserved1 pointExample Response1 $\Sigma p_0 = \Sigma p_f$ $m_A v_{A0} + m_B v_{B0} = m_A v_{Af} + m_B v_{Bf}$ $m_A v_{A0} - m_A v_{Af} = m_B v_{Bf}$ For the correct answer for speed with units (2 m/s)1 point

### **Example Solution**

$$m_{\rm A}v_{\rm A0} + m_{\rm B}v_{\rm B0} = m_{\rm A}v_{\rm Af} + m_{\rm B}v_{\rm Bf}$$
$$m_{\rm A}v_{\rm A0} - m_{\rm A}v_{\rm Af} = m_{\rm B}v_{\rm Bf}$$
$$v_{\rm Bf} = \frac{m_{\rm A}}{m_{\rm B}}(v_{\rm A0} - v_{\rm Af})$$
$$\rightarrow v_{\rm Bf} = \frac{1000 \text{ kg}}{2000 \text{ kg}}(5 \text{ m/s} - 1 \text{ m/s})$$

 $\therefore v_{\rm Bf} = 2 \, {\rm m/s}$ 

(a)(iii)	For a graph that starts at $(0,0)$ and ends at $(0.5,2)$ or value consistent with (a)(ii)	1 point
	For a smooth, continuous curve that transitions from concave up to concave down	1 point



Total for part (a) 5 points

### (b)(i) For indicating the derivative of the velocity function is the acceleration of the cart

1 point

### **Example Response**

$$a(t) = \frac{dv}{dt}$$
  

$$\rightarrow a(t) = \frac{d(64t^3 - 48t^2 + 5)}{dt}$$
  

$$\therefore a(t) = 192t^2 - 96t$$

For setting the derivative of the previously derived expression for acceleration equal to zero **1 point** 

### **Example Response**

$$\frac{d}{dt}a(t) = 0$$
$$0 = 384t - 96$$

For indicating the maximum acceleration is  $12 \text{ m/s}^2$  or maximum acceleration occurs at time **1 point** t = 0.25 s

### **Example Response**

0 = 384t - 96 $\therefore t_{\text{max}} = 0.25 \text{ s}$ 

For substituting the time at which the acceleration is a maximum or the maximum1 pointacceleration into an expression of Newton's second law to calculate the value of the<br/>maximum force1

### **Example Response**

$$F(t) = ma(t)$$
  

$$F_{\text{max}} = ma(0.25 \text{ s})$$

### **Example Solution**

$$a(t) = \frac{dv}{dt}$$
  

$$\rightarrow a(t) = \frac{d(64t^3 - 48t^2 + 5)}{dt}$$
  

$$\therefore a(t) = 192t^2 - 96t$$
  

$$\frac{d}{dt}a(t) = 0$$
  

$$\frac{d(192t^2 - 96t)}{dt} = 0$$
  

$$\rightarrow 0 = 384t - 96$$
  

$$\therefore t_{max} = 0.25 \text{ s}$$
  

$$F(t) = ma(t)$$
  

$$F_{max} = ma(0.25 \text{ s})$$
  

$$F_{max} = (1000 \text{ kg})(192(0.25 \text{ s})^2 - 96(0.25 \text{ s}))$$
  

$$\therefore |F_{max}| = 12,000 \text{ N}$$

Alternate Solution	
For indicating the derivative of the momentum function is the force exerted on the cart	1 point
Alternate Example Response	
$F(t) = \frac{dp}{dt}$	
$F(t) = \frac{d}{dt}(64000t^3 - 48000t^2 + 5000)$	
For setting the derivative of the previously derived expression for force equal to zero	1 point
Alternate Example Response	
$\frac{d}{dt}F(t) = 0$	
$\frac{d}{dt} \left( 192000t^2 - 96000t \right) = 0$	
For indicating the maximum force occurs at time $t = 0.25$ s	1 point
Alternate Example Response	
0 = 384000t - 96000	
$\therefore t_{\text{max}} = 0.25 \text{s}$	
For substituting the time at which the force is at a maximum into an expression for	1 point
momentum to calculate the value of the maximum force	
Alternate Example Response	
$F(t) = \frac{d}{dt}p(t)$	
$F_{\rm max} = \frac{d}{dt}  p(0.25  \rm s)$	

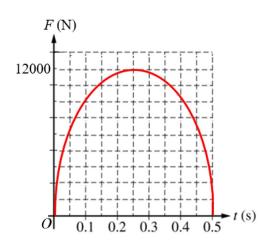
Alternate Example Solution  

$$p(t) = mv(t)$$
  
 $\rightarrow p(t) = (1000 \text{ kg})(64t^3 - 48t^2 + 5)$   
 $\therefore p(t) = 64000t^3 - 48000t^2 + 5000$   
 $F(t) = \frac{dp}{dt}$   
 $\rightarrow F(t) = \frac{d}{dt}(64000t^3 - 48000t^2 + 5000)$   
 $\therefore F(t) = 192000t^2 - 96000t$   
 $\frac{d}{dt}F(t) = 0$   
 $\frac{d}{dt}(192000t^2 - 96000t) = 0$   
 $\rightarrow 0 = 384000t - 96000$   
 $\therefore t_{\text{max}} = 0.25 \text{ s}$   
 $F(t) = \frac{d}{dt}p(t)$   
 $F_{\text{max}} = \frac{d}{dt}p(0.25 \text{ s})$ 

 $F_{\text{max}} = 192000(0.25 \text{ s})^2 - 96000(0.25 \text{ s})$  $\therefore |F_{\text{max}}| = 12,000 \text{ N}$ 

(b)(ii)	For a curve that increases and then decreases in value that is only concave down	1 point
	For a labeled maximum value consistent with the calculated value in part (b)(i)	1 point
	For the graph having values of 0 N at $t = 0$ s and $t = 0.5$ s	1 point

### **Example Solution**



	Total for part (b)	7 points
(c)	For selecting $F_1 < F_2$ with an attempt at a relevant justification	1 point
	For indicating that the impulse or change in momentum of each cart in both collisions is the same	1 point
	For indicating that decreasing the time of collision means the average force must be greater	1 point
	Example Solution	

Since the initial and final velocities are the same for both collisions,  $\Delta p$  is the same for both collisions; as a result, the impulse is the same for both collisions. So, if  $\Delta t$  is smaller,  $F_{avg}$  is larger.

Total for	r part (c)	3 points
Total for q	uestion 1	15 points

### **Question 2: Free-Response Question**

(a) For indicating the equivalent spring constant  $k_{eq}$  is the sum of the spring constants of all the **1 point** springs arranged in parallel

### Example Response

$$k_{\rm eq} = Nk$$

For a correct expression for period consistent with  $k_{eq}$  above

**Example Response** 

$$T = 2\pi \sqrt{\frac{m}{Nk}}$$

**Example Solution** 

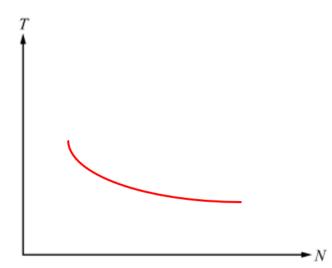
$$k_{eq} = \sum_{i=1}^{N} k_i$$
  

$$k_{eq} = Nk$$
  

$$T = 2\pi \sqrt{\frac{m}{Nk}}$$

	Total for part (a)	2 points
(b)	For a graph that increases or decreases with $N$ consistent with the expression derived in part (a)	1 point
	For a concavity that is consistent with the expression derived in part (a)	1 point

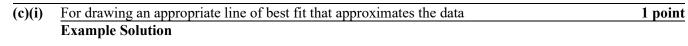
### **Example Solution**

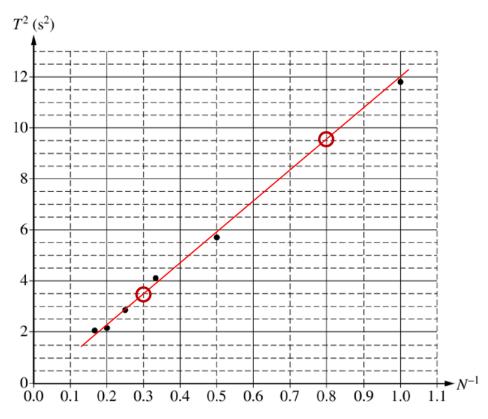


Scoring Note: The student is not required to label N = 1 on the horizontal axis, so the curve can start at the vertical axis, implying that N = 1 is at the origin.

Scoring Note: Discrete points following the appropriate curve will earn this point.

15 points





### (c)(ii) For using two points from the best-fit line to calculate slope

# **Scoring Note:** Using data points that fall on the best-fit line is acceptable. **Example Response**

slope = 
$$\frac{\Delta(T^2)}{\Delta(N^{-1})}$$
  
slope =  $\frac{(9.5 \text{ s}^2 - 3.5 \text{ s}^2)}{(0.8 - 0.3)}$   
∴ slope =  $12 \text{ s}^2$ 

For relating the slope of the line of the  $T^2$  vs.  $N^{-1}$  graph consistent with the expression **1** point derived in part (a)

### Example Response

$$T^{2} = 4\pi^{2} \frac{m}{Nk}$$
  
slope =  $T^{2}N$   
slope =  $4\pi^{2} \frac{m}{k}$ 

For a calculated answer that has units of N/m

### **Example Response**

 $\frac{k = 4.93 \text{ N/m}}{\text{Example Solution}}$ 

$$T^{2} = 4\pi^{2} \frac{m}{Nk}$$
  
slope =  $4\pi^{2} \frac{m}{k}$   
 $k = \frac{4\pi^{2}m}{\text{slope}}$   
 $k = \frac{4\pi^{2}(1.5 \text{ kg})}{\frac{(9.5 \text{ s}^{2} - 3.5 \text{ s}^{2})}{(0.8 - 0.3)}}$   
 $\rightarrow k = \frac{4\pi^{2}(1.5 \text{ kg})}{12 \text{ s}^{2}}$   
 $k = 4.93 \text{ N/m}$ 

(c)(iii) For indicating a source of error that could result in the observed difference with an attempt at a relevant justification 1 point

Examples include:

- Experimental uncertainties in the mass of the system
- Motion detector miscalibration
- Timing error due to reaction time

For a correct justification that links the source of experimental error to the smaller experimental value of k

Examples include:

- Experimental uncertainties in the mass of the system (e.g., mass of block is too small, not accounting for the mass of the spring)
- Calibration of the motion sensor produces a graph from which too large a period is measured
- A larger period due to measurement error will result in a smaller value of k

		Total for part (c)	6 points
(d)(i)	For indicating that the slope would not change with an attempt at a relevant	nt justification	1 point
	For a justification that the period depends on the mass and spring constant unchanged	which remain	1 point

### OR

## For a justification that indicates that the period is independent of gravitational force **Example Solution**

The period of oscillation of the spring-block system depends on the mass and the effective spring constant,  $T = 2\pi \sqrt{\frac{m}{Nk}}$ . The slope is equal to the square of the period over the inverse number of identical springs, Slope =  $\frac{T^2}{N^{-1}}$ . This means that the slope is proportional

to the mass divided by the spring constant. Since neither the mass nor the spring constant change, the slope will remain unchanged.

### OR

The period of oscillation of the spring-block system depends on the mass and the effective spring constant,  $T = 2\pi \sqrt{\frac{m}{Nk}}$ . The slope is equal to the square of the period over the inverse number of identical springs,  $Slope = \frac{T^2}{N^{-1}}$ . Since the period is independent of the gravitational force, and the only change was arranging the block-spring system horizontally instead of vertically, the period is not affected by the change in the orientation of the system. Therefore, the slope will remain unchanged.

(d)(ii)	For a relationship between $v_{\text{max}}$ and N that is consistent with the expression from part (a)	1 point
	with an attempt at relevant justification	
	For using energy conservation to justify the relationship	1 point

### OR

For using the relationship between  $v_{\text{max}}$  and  $\omega$  to justify the relationship

For indicating that the effective spring constant changes the elastic potential energy of the spring block system  $U_s$  therefore changing  $v_{max}$  in a manner consistent with the expression from part (a)

### OR

For an inverse relationship between  $\omega$  and period, indicating a change in  $v_{\text{max}}$  consistent with the expression from part (a)

### **Example Solution**

An increase in the number of identical springs attached in parallel to each other causes the

effective spring constant to increase,  $k_{eff} = \sum_{i=1}^{N} k_i$ . Since the effective spring constant is

proportional to potential energy of the block-spring system,  $U_s = \frac{1}{2}k_{eff}x^2$ , an increase in

the effective spring constant causes the potential energy of the block-spring system to increase for a given displacement. Therefore, based on conservation of energy,

 $\frac{1}{2}k_{\text{eff}}x^2 = \frac{1}{2}mv_{\text{max}}^2$ , an increase in the potential energy will cause an increase in the kinetic

energy, resulting in a greater maximum velocity. Therefore, the maximum velocity will increase with an increase in the number of springs added.

### OR

An increase in the number of identical springs attached in parallel to each other causes the effective spring constant to increase,  $k_{\text{eff}} = \sum_{i=1}^{N} k_i$ . Since the effective spring constant is

inversely proportional to the period of oscillation of the block-spring system,  $T = 2\pi \sqrt{\frac{m}{k_{\text{eff}}}}$ , an increase in the effective spring constant causes the period to decrease. Since the period is inversely proportional to the angular frequency of the block-spring system,  $\omega = \frac{2\pi}{T}$ , the

angular frequency increases. Since the maximum velocity is proportional to the angular frequency,  $v_{max} = x_0 \omega$ , this results in an increase in the maximum velocity. Therefore, the maximum velocity will increase with an increase in the number of springs added.

Total for part (d) 5 points

Total for question 2 15 points

### Question 3: Free-Response Question

### (a) For stating the parallel axis theorem 1 point

### **Example Response**

$$I_{\text{blade}} = I_{\text{CM}} + Md^2$$

For using correct substitutions of the rotational inertia of one blade about its center of mass **1 point** and substituting the distance from the center of mass

Example Response

$$I_{\text{blade}} = \frac{1}{18}ML^2 + M\left(\frac{L}{3}\right)^2$$

For multiplying the rotational inertia of one blade by 3

1 point

15 points

**Example Response** 

$$I_{\rm rotor} = 3I_{\rm blade} = \frac{1}{2}ML^2$$

**Example Solution** 

$$I_{\text{blade}} = I_{\text{CM}} + Md^2$$
$$I_{\text{blade}} = \frac{1}{18}ML^2 + M\left(\frac{L}{3}\right)^2$$
$$I_{\text{blade}} = \frac{1}{6}ML^2$$
$$I_{\text{rotor}} = 3I_{\text{blade}} = \frac{1}{2}ML^2$$

Total for par	rt (a)	3 points

(b)	For calculating the correct answer with correct units $(2.4 s)$	1 point
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### **Example Solution**

$$v = r\omega$$

$$v = L\omega_0$$

$$\frac{d}{t} = L\omega_0$$

$$t = \frac{d}{L\omega_0} = \frac{2\pi L}{L\omega_0} = \frac{2\pi}{\omega_0}$$

$$t = \frac{2\pi}{(2.6 \text{ rad/s})}$$

$$\therefore t = 2.4 \text{ s}$$

Total for part (b) 1 point

### (c)(i) For indicating that the total initial rotational kinetic energy is dissipated

### 1 point

### Example Response

$$\Delta K_{\rm rot} = E_{\rm dis}$$
$$0 - \frac{1}{2} I \omega_0^2 = E_{\rm dis}$$

For substituting correct values for the rotational inertia and initial angular speed of the system **1 point** 

### **Example Response**

$$E_{\rm dis} = -\frac{1}{2} (6.7 \times 10^6 \text{ kg} \cdot \text{m}^2) (2.6 \text{ rad/s})^2$$

For an answer consistent with substitutions above and with correct units

1 point

### **Example Response**

$$E_{\rm dis} = -2.3 \times 10^7 \, {\rm J}$$

### **Example Solution**

$$\Delta K_{\text{rot}} = E_{\text{dis}}$$

$$0 - \frac{1}{2} I \omega_0^2 = E_{\text{dis}}$$

$$E_{\text{dis}} = -\frac{1}{2} (6.7 \times 10^6 \text{ kg} \cdot \text{m}^2) (2.6 \text{ rad/s})^2$$

$$E_{\text{dis}} = -2.3 \times 10^7 \text{ J}$$

Scoring Note: A response may earn full credit for positive or negative values of dissipated energy.

(c)(ii)	For using Newton's second law in rotational form	1 point
	For attempting to differentiate the equation for $\omega$	1 point

### **Example Response**

$$\tau = I_{\rm sys} \frac{d}{dt} \Big( \omega_0 e^{-\beta_0 t} \Big)$$

For a correct expression for the torque on the system

Example Response

$$\tau = -\beta_0 I_{\rm sys} \omega_0 e^{-\beta_0 t}$$

**Example Solution** 

$$\tau = I\alpha$$
  

$$\tau = I_{\text{sys}} \frac{d\omega}{dt}$$
  

$$\tau = I_{\text{sys}} \frac{d}{dt} (\omega_0 e^{-\beta_0 t})$$
  

$$\therefore \tau = -\beta_0 I_{\text{sys}} \omega_0 e^{-\beta_0 t}$$

### (c)(iii) For attempting to integrate the expression for angular speed

### Example Response

$$\Delta\theta = \int \omega(t) dt$$

For using the correct limits of integration

### **Example Response**

$$\Delta\theta = \int_{0}^{t} \omega_{0} e^{-\beta_{0} t} dt$$

For a correct expression for angular displacement

### **Example Response**

$$\Delta\theta = \frac{\omega_0}{\beta_0} \left(1 - e^{-\beta_0 t}\right)$$

### **Example Solution**

$$\Delta \theta = \int \omega(t) dt$$
  

$$\Delta \theta = \int_{0}^{t} \omega_{0} e^{-\beta_{0}t} dt$$
  

$$\Delta \theta = \left( -\frac{\omega_{0}}{\beta_{0}} e^{-\beta_{0}t} \right) \Big|_{0}^{t} = -\frac{\omega_{0}}{\beta_{0}} e^{-\beta_{0}t} + \frac{\omega_{0}}{\beta_{0}} (1)$$
  

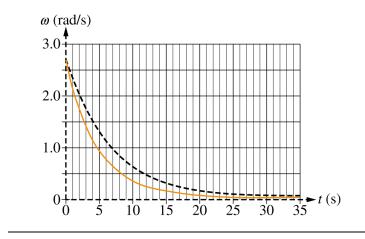
$$\therefore \Delta \theta = \frac{\omega_{0}}{\beta_{0}} (1 - e^{-\beta_{0}t})$$

Total for part (c) 9 points

1 point

(d)	For drawing a continuous curve showing an exponential decay	1 point
	For starting at $\omega = 2.6$ rad/s and drawing a curve below the original curve	1 point

### **Example Solution**



Total for part (d) 2 points

Total for question 3 15 points