ADVANCED PLACEMENT PHYSICS 2 TABLE OF INFORMATION

UNIT SYMBOLS

A

C

 $^{\circ}C$

eV

Hz J

K

kg

m

N

Ω

Pa

S

Τ V

W

mol

F

ampere,

coulomb,

degree Celsius,

electron volt,

farad.

hertz,

joule,

kelvin,

kilogram,

meter,

mole,

newton.

ohm.

pascal,

second,

tesla,

volt,

watt,

Avogadro's number,	$N_0 = 6.02 \times 10^{23} \text{ mol}^{-1}$

 $R = 8.31 \text{ J/(mol \cdot K)}$ Universal gas constant, $k_{\rm B} = 1.38 \times 10^{-23} \text{ J/K}$ Boltzmann's constant,

 $1 \text{ atm} = 1.0 \times 10^5 \text{ N/m}^2 = 1.0 \times 10^5 \text{ Pa}$ 1 atmosphere of pressure,

CONSTANTS AND CONVERSION FACTORS

 $k = \frac{1}{4\pi\varepsilon_0} = 9.0 \times 10^9 \frac{\text{N} \cdot \text{m}^2}{\text{C}^2}$ Coulomb constant.

 $m_n = 1.67 \times 10^{-27} \text{ kg}$ Proton mass. $m_{..} = 1.67 \times 10^{-27} \text{ kg}$ Neutron mass. $m_a = 9.11 \times 10^{-31} \text{ kg}$ Electron mass. $e = 1.60 \times 10^{-19} \text{ C}$ Elementary charge,

 $\varepsilon_0 = 8.85 \times 10^{-12} \text{ C}^2 / (\text{N} \cdot \text{m}^2)$ Vacuum permittivity, $\mu_0 = 4\pi \times 10^{-7} \ (\text{T} \cdot \text{m})/\text{A}$ Vacuum permeability,

 $1 \text{ eV} = 1.60 \times 10^{-19} \text{ J}$ 1 electron volt.

 $h = 6.63 \times 10^{-34} \text{ J} \cdot \text{s} = 4.14 \times 10^{-15} \text{ eV} \cdot \text{s}$ Planck's constant,

 $hc = 1.99 \times 10^{-25} \text{ J} \cdot \text{m} = 1240 \text{ eV} \cdot \text{nm}$

 $c = 3.00 \times 10^8 \text{ m/s}$ Speed of light, $b = 2.90 \times 10^{-3} \text{ m} \cdot \text{K}$ Wien's constant,

Stefan-Boltzmann constant.

 $\sigma = 5.67 \times 10^{-8} \text{ W/(m}^2 \cdot \text{K}^4)$ 1 u = 1.66×10⁻²⁷ kg = 931 MeV/ c^2 1 unified atomic mass unit,

Universal gravitational constant

Magnitude of the acceleration of

Magnitude of the gravitational

t, $G = 6.67 \times 10^{-11} \text{ m}^3/(\text{kg} \cdot \text{s}^2) = 6.67 \times 10^{-11} \text{ N} \cdot \text{m}^2/\text{kg}^2$ due to gravity at Earth's surface, $g = 9.8 \text{ m/s}^2$ field strength at the Earth's surface, $g = 9.8 \text{ N/kg}$							
VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
θ	0°	30°	37°	45°	53°	60°	90°
$\sin \theta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
$\tan \theta$	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	8

PREFIXES		
Factor	Prefix	Symbol
10 ¹²	tera	Т
10 ⁹	giga G	
10^{6}	mega M	
10^{3}	kilo	k
10^{-2}	centi	С
10^{-3}	milli	m
10^{-6}	micro	μ
10 ⁻⁹	nano	n
10^{-12}	pico	p

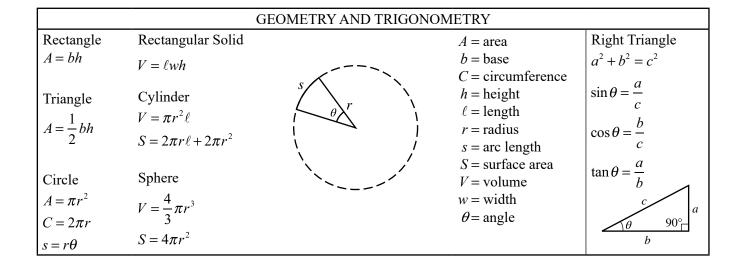
The following conventions are used in this exam:

- The frame of reference of any problem is assumed to be inertial unless otherwise stated.
- Air resistance is assumed to be negligible unless otherwise stated.
- In all situations, positive work is defined as work done **ON** a system
- Springs and strings are assumed to be ideal unless otherwise stated.
- The electric potential is zero at an infinite distance from an isolated point charge.
- The direction of current is the direction in which positive charges would drift.
- All batteries and meters are assumed to be ideal unless otherwise stated.

ELECTRICITY		MAGNETISM		
$\begin{split} \left \vec{F}_E \right &= \frac{1}{4\pi\varepsilon_0} \frac{\left q_1 q_2 \right }{r^2} = k \frac{\left q_1 q_2 \right }{r^2} \\ \vec{E} &= \frac{\vec{F}_E}{q} \\ \left \vec{E} \right &= \frac{1}{4\pi\varepsilon_0} \frac{\left q \right }{r^2} = k \frac{\left q \right }{r^2} \\ U_E &= \frac{1}{4\pi\varepsilon_0} \frac{q_1 q_2}{r} = k \frac{q_1 q_2}{r} \\ \Delta V &= \frac{\Delta U_E}{q} \\ V &= \frac{1}{4\pi\varepsilon_0} \sum_i \frac{q_i}{r_i} \\ \left \vec{E} \right &= \left \frac{\Delta V}{\Delta r} \right \\ C &= \kappa\varepsilon_0 \frac{A}{d} \end{split}$	$A = area$ $C = capacitance$ $d = distance$ $E = electric field$ $E = force$ $E = current$ $\ell = length$	$F_{B} = qvB\sin\theta$ $B = \frac{\mu_{0}I}{2\pi r}$ $F_{B} = I\ell B\sin\theta$ $\Phi_{B} = \vec{B} \cdot \vec{A}$ $\Phi_{B} = \vec{B} \cos\theta \vec{A} $ $ \mathcal{E} = \left \frac{\Delta\Phi_{B}}{\Delta t}\right $ $\mathcal{E} = R\ell v$	$A = \text{area}$ $B = \text{magnetic field}$ $F = \text{force}$ $I = \text{current}$ $\ell = \text{length}$ $q = \text{charge}$ $r = \text{distance, radius, or position}$ $t = \text{time}$ $v = \text{velocity or speed}$ $\mathcal{E} = \text{emf}$ $\theta = \text{angle}$ $\Phi = \text{flux}$	
$E_C = \frac{Q}{\kappa \varepsilon_0 A}$		THE	RMAL PHYSICS	
$U_{C} = \frac{1}{2}Q\Delta V$ $I = \frac{\Delta Q}{\Delta t}$ $R = \frac{\rho \ell}{A}$ $P = I\Delta V$ $I = \frac{\Delta V}{R}$ $R_{eq,s} = \sum_{i} R_{i}$ $\frac{1}{R_{eq,p}} = \sum_{i} \frac{1}{R_{i}}$ $\frac{1}{C_{eq,s}} = \sum_{i} \frac{1}{C_{i}}$ $C_{eq,p} = \sum_{i} C_{i}$		$P = \frac{F_{\perp}}{A}$ $K_{\text{avg}} = \frac{3}{2} k_{\text{B}} T = \frac{1}{2} m v_{\text{rms}}^{2}$ $\frac{Q}{\Delta t} = \frac{kA\Delta T}{L}$ $PV = nRT = Nk_{\text{B}} T$ $U = \frac{3}{2} nRT = \frac{3}{2} Nk_{\text{B}} T$ $W = -P\Delta V$ $\Delta U = Q + W$ $Q = mc\Delta T$		

 $\tau = R_{\rm eq} C_{\rm eq}$

WAVES, SOUND, AND OPTICS	MODERN PHYSICS		
$\lambda = \frac{v}{f}$ $a = \text{width}$ $A = \text{amplitude}$ $d = \text{separation}$ $D = \text{path length}$ $f = \text{frequency or focal length}$ $\frac{1}{s_i} + \frac{1}{s_o} = \frac{1}{f}$ $F = \text{force}$ $h = \text{height}$ $ M = \left \frac{h_i}{h_o} \right = \left \frac{s_i}{s_o} \right $ $\Delta D = m\lambda$ $\Delta D = m\lambda$ $\Delta D = a \sin \theta$ $a \left(\frac{y_{\min}}{L} \right) \approx m\lambda$ $\Delta D = d \sin \theta$ $d \left(\frac{y_{\max}}{L} \right) \approx m\lambda$ $v = \text{speed}$ $d \left(\frac{y_{\max}}{L} \right) \approx m\lambda$ $v = \text{position}$ $\lambda = \text{wavelength}$ $\theta = \text{angle}$ $\theta = \text{angle}$ $\theta = \text{angular frequency}$ $T = \frac{1}{f}$ $x(t) = A \cos(\omega t) = A \cos(2\pi f t)$ $y(x) = A \cos\left(2\pi \frac{x}{\lambda}\right)$ $ f_{\text{beat}} = f_1 - f_2 $	$E = hf$ $\lambda = \frac{h}{p}$ $E = energy$ $f = frequency$ $K = kinetic energy$ $m = mass$ $\lambda_{max} = \frac{b}{T}$ $N = number of particles$ $p = momentum$ $P = A\sigma T^4$ $P = power$ $K_{max} = hf - \phi$ $T = absolute temperature$ $\Delta \lambda = \frac{h}{m_e c} (1 - \cos \theta)$ $E = mc^2$ $N = N_0 e^{-\lambda t}$ $\lambda = \frac{\ln 2}{t_{1/2}}$ $A = area$ $b = constant$ $P = hriching for energy$ $t = time$ $T = absolute temperature$ $\theta = angle$ $\lambda = wavelength or decay$ $constant$ $\sigma = constant$ $\phi = work function$		



MECHANICS AND FLUIDS

a = acceleration

d = distance

J = impulse

K = kinetic energy

p = momentum

position

E = energy

F =force

m = mass

P = power

t = time

W = work

x = position

y = height

 θ = angle

$v_{x} = v_{x0} + a_{x}t$
$x = x_0 + v_{x0}t + \frac{1}{2}a_xt^2$
$v_x^2 = v_{x0}^2 + 2a_x(x - x_0)$
$\vec{x}_{\rm cm} = \frac{\sum m_i \vec{x}_i}{\sum m_i}$
$\vec{a}_{\rm sys} = \frac{\sum \vec{F}}{m_{\rm sys}} = \frac{\vec{F}_{\rm net}}{m_{\rm sys}}$
$\left \vec{F}_{g} \right = G \frac{m_{1} m_{2}}{r^{2}}$
$\left \vec{F}_f \right \leq \left \mu \vec{F}_n \right $
$\vec{F}_s = -k\Delta \vec{x}$
$a_c = \frac{v^2}{r}$
$K = \frac{1}{2}mv^2$
$W = F_{\parallel} d = F d \cos \theta$
$\Delta K = \sum_{i=1}^{n} W_{i} = \sum_{i=1}^{n} F_{\parallel,i} d_{i}$
$\Delta U_s = \frac{1}{2}k(\Delta x)^2$
$U_G = -\frac{Gm_1m_2}{r}$
$\Delta U_{g} = mg\Delta y$
$P_{\text{avg}} = \frac{W}{\Delta t} = \frac{\Delta E}{\Delta t}$
$P_{\text{inst}} = F_{\parallel} v = F v \cos \theta$
$\vec{p} = m\vec{v}$
$\vec{F}_{\text{net}} = \frac{\Delta \vec{p}}{\Delta t} = m \frac{\Delta \vec{v}}{\Delta t} = m \vec{a}$
$\vec{J} = \vec{F}_{ m avg} \Delta t = \Delta \vec{p}$
$\vec{v}_{\rm cm} = \frac{\sum \vec{p}_i}{\sum m_i} = \frac{\sum m_i \vec{v}_i}{\sum m_i}$

k = spring constantr = radius, distance, or U = potential energyv = velocity or speed μ = coefficient of friction

 $\omega = \omega_0 + \alpha t$ $\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$ $\omega^2 = \omega_0^2 + 2\alpha (\theta - \theta_0)$ $v = r\omega$ $a_r = r\alpha$ $\tau = r_{\perp}F = rF\sin\theta$ $I = \sum m_i r_i^2$ $I' = I_{cm} + Md^2$ $\alpha_{\rm sys} = \frac{\Sigma \tau}{I_{\rm sys}} = \frac{\tau_{\rm net}}{I_{\rm sys}}$ $K = \frac{1}{2}I\omega^2$ $W = \tau \Delta \theta$ $L = I\omega$ $L = rmv \sin \theta$ $\Delta L = \tau \Delta t$ $\Delta x_{\rm cm} = r\Delta\theta$ $T = \frac{1}{f}$ $T_s = 2\pi \sqrt{\frac{m}{k}}$ $T_p = 2\pi \sqrt{\frac{\ell}{\alpha}}$ $x = A\cos(2\pi ft)$ $x = A\sin(2\pi ft)$ $P = \frac{F_{\perp}}{A}$ $P = P_0 + \rho g h$ $P_{\text{gauge}} = \rho g h$ $F_b = \rho V g$ $A_1 V_1 = A_2 V_2$

a = accelerationA =amplitude or area d = distancef = frequencyF =force h = heightI = rotational inertiak =spring constant K = kinetic energy $\ell = length$ L = angular momentumm = massM = massP = pressurer = radius, distance, or position t = timeT = periodv =velocity or speed V = volumeW = workx = positiony = vertical position α = angular acceleration θ = angle ρ = density τ = torque ω = angular speed $P_1 + \rho g y_1 + \frac{1}{2} \rho v_1^2 = P_2 + \rho g y_2 + \frac{1}{2} \rho v_2^2$